

Analysis of a model for adhesive contact with thermal effects

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joint work with

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Frémond's modeling of adhesive contact

Setting

A viscoelastic body $\Omega \subset \mathbb{R}^3$ in **adhesive contact** with a rigid support on a **(flat)** part Γ_{Cont} of its boundary $\partial\Omega = \Gamma_{\text{Dir}} \cup \Gamma_{\text{Neu}} \cup \Gamma_{\text{Cont}}$.

Related contributions

.... Andrews, Cangémi, Chau, Cocou, Eck, Fernández, Figuereido, Han, Jarušek, Klarbring, Krbec, Kuttler, Martins, Muñoz-Rivera, Point, Racke, Raous, Shi, Shillor, Sofonea, Telega, Trabucho, Wright.....

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Based on [M. Frémond, *Non-smooth Thermomechanics*, 2002]

Account for **microscopic motions** in the **macroscopic predictive theory**

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- ▶ microscopic bonds are responsible for the adhesion, microscopic motions lead to rupture

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Account for **microscopic motions** in the **macroscopic predictive theory**

- ▶ microscopic bonds are responsible for the adhesion, microscopic motions lead to rupture
- ▶ account for the **power of the microscopic motions** in the power of the interior forces

State variables

In the **isothermal case** [Bonetti-Bonfanti-R. '07,'08]

- ▶ in the **volume domain** Ω :
 - ▶ **small deformation** ($\varepsilon(\mathbf{u})$ symm. linear. strain tensor) (**small perturbation assumption**)
 - ▶
- ▶ on the **contact surface** Γ_{Cont} :
 - ▶ **adhesion** (χ “phase parameter” related to the active bonds of the adhesion \rightsquigarrow “damage parameter”)
 - ▶ **effects of displacement** ($\mathbf{u}|_{\Gamma_{\text{Cont}}}$ trace of the displacement)
 - ▶

State variables

To account for **thermal effects**: [Bonetti-Bonfanti-R. preprint'08]

- ▶ in the **volume domain** Ω :
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 - ▶ **thermal effects** (θ_s absolute temperature)

The equations for \mathbf{u} and χ

From the **principle of virtual power** (interior & exterior forces, no acceleration forces)

► **momentum balance:**

$$\left\{ \begin{array}{l} -\operatorname{div} \Sigma = \mathbf{f} \quad \text{in } \Omega \times (0, T), \\ \left\{ \begin{array}{l} \Sigma \mathbf{n} = \mathbf{R} \quad \text{in } \Gamma_{\text{Cont}} \times (0, T), \\ \mathbf{u} = \mathbf{0} \quad \text{in } \Gamma_{\text{Dir}} \times (0, T), \\ \Sigma \mathbf{n} = \mathbf{g} \quad \text{in } \Gamma_{\text{Neu}} \times (0, T), \end{array} \right. \end{array} \right.$$

$$\left\{ \begin{array}{l} \Sigma \text{ stress tensor} \\ \mathbf{R} \text{ reaction on the contact surface} \\ \mathbf{f} \text{ volume force, } \mathbf{g} \text{ traction} \end{array} \right.$$

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► **equation for the microscopic motions:**

$$\left\{ \begin{array}{l} B - \operatorname{div} \mathbf{H} = 0 \quad \text{in } \Gamma_{\text{Cont}} \times (0, T), \\ \mathbf{H} \cdot \mathbf{n}_s = 0 \quad \text{on } \partial\Gamma_{\text{Cont}} \times (0, T), \end{array} \right.$$

$$\left\{ \begin{array}{l} B \text{ interior microscopic work} \\ \mathbf{H} \text{ microscopic work flux vector} \end{array} \right.$$

The equations for θ and θ_s

Entropy balance for θ and θ_s :

► for θ :

$$\begin{cases} s_t + \operatorname{div} \mathbf{Q} = h & \text{in } \Omega \times (0, T), \\ \mathbf{Q} \cdot \mathbf{n} = F & \text{on } \Gamma_{\text{Cont}} \times (0, T), \\ \mathbf{Q} \cdot \mathbf{n} = 0 & \text{on } \partial\Omega \setminus \Gamma_{\text{Cont}} \times (0, T), \end{cases}$$

$$\begin{cases} s & \text{internal entropy} \\ \mathbf{Q} & \text{entropy flux vector} \\ h & \text{entropy source,} \\ F & \text{entropy flux through } \Gamma_{\text{Cont}} \end{cases}$$

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► for θ_s :

$$\begin{cases} \partial_t s_s + \operatorname{div} \mathbf{Q}_s = F & \text{in } \Omega \times (0, T), \\ \mathbf{Q}_s \cdot \mathbf{n}_s = 0 & \text{on } \partial\Gamma_{\text{Cont}} \times (0, T), \end{cases}$$

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Entropy balance: obtained by rescaling the internal energy balance (under small perturbation assumpt.): see [\[Bonetti-Frémond'03, Bonetti-Colli-Frémond'03, Bonetti'06, Bonetti-Colli-Fabrizio-Gilardi'06,'07,08, Bonetti-Rocca-Frémond'07\]](#)

Constitutive laws

Constitutive relations for

$$\Sigma, \mathbf{R}, s, \mathbf{Q}, F, B, \mathbf{H}, s_s, \mathbf{Q}_s$$

derive from the **volume & surface free energies**

$$\Psi_\Omega = \Psi_\Omega(\mathbf{u}, \theta), \quad \Psi_{\Gamma_{\text{Cont}}} = \Psi_{\Gamma_{\text{Cont}}}(\mathbf{u}|_{\Gamma_{\text{Cont}}}, \chi, \theta_s)$$

and the **pseudo-potentials of dissipation**

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Constraints

- ▶ admissible values for χ and (possibly) irreversibility
- ▶ impenetrability condition between the body and the support
- ▶ positivity of the absolute temperatures θ and θ_s

The adhesion phenomenon

The “damage parameter” χ denotes the **fraction of active glue fibers** at each point of the contact surface

- ▶ $\chi = 0$ no adhesion (completely broken bonds)
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Physical constraints

- ▶ $\chi \in [0, 1]$
- ▶ $\chi_t \leq 0$ (irreversible phenomenon)

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Physical constraints

- ▶ $\chi \in [0, 1]$

As a first step, neglect irreversibility (\sim fresh, liquid glue..)

Unilateral conditions

The **impenetrability condition**

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If $\chi = 0$ (no adhesion) the reaction on Γ_{Cont} is

$$\mathbf{R} = -\partial l_{[-\infty, 0]}(\mathbf{u} \cdot \mathbf{n})\mathbf{n}$$

(omitting traces) where

$$\partial l_{[-\infty, 0]}(\mathbf{u} \cdot \mathbf{n}) = \begin{cases} 0 & \text{if } \mathbf{u} \cdot \mathbf{n} < 0 \\ [0, +\infty[& \text{if } \mathbf{u} \cdot \mathbf{n} = 0 \end{cases}$$

- ▶ \mathbf{R} is normal to Γ_{Cont}
- ▶ $\mathbf{R} = \mathbf{0}$ if $\mathbf{u} \cdot \mathbf{n} < 0$
- ▶ $\mathbf{R} = \gamma\mathbf{n}$, $\gamma \leq 0$ if $\mathbf{u} \cdot \mathbf{n} = 0$

This is in agreement with the **Signorini conditions**

Unilateral conditions

The **impenetrability condition**

$$\mathbf{u}|_{\Gamma_{\text{Cont}}} \cdot \mathbf{n} \leq 0 \quad \text{on } \Gamma_{\text{Cont}}.$$

is ensured by the reaction on the contact surface

In the case the adhesion is active $\chi > 0$

$$\mathbf{R} = -\chi \mathbf{u} - \partial \mathbf{l}_{]-\infty, 0]}(\mathbf{u} \cdot \mathbf{n}) \mathbf{n}$$

i.e., there is a reaction (with rigidity $\sim \chi$) **counteracting separation:**

$$\mathbf{R} \cdot \mathbf{n} = -\chi \mathbf{u} \cdot \mathbf{n} > 0 \text{ if } \mathbf{u} \cdot \mathbf{n} < 0$$

The PDE system: the momentum balance

Recall $\Omega \subset \mathbb{R}^3$ smooth, bounded and $\partial\Omega = \Gamma_{\text{Dir}} \cup \Gamma_{\text{Neu}} \cup \Gamma_{\text{Cont}}$

- ▶ The momentum balance

$$-\operatorname{div} (K\varepsilon(\mathbf{u}) + K_v\varepsilon(\mathbf{u}_t) + \theta\mathbf{1}) = \mathbf{f} \quad \text{in } \Omega \times (0, T)$$

where: K elasticity tensor, K_v viscosity tensor, $\theta\mathbf{1} \leftrightarrow$ **thermal deformation**

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- ▶ the **boundary conditions**

$$\mathbf{u} = \mathbf{0} \quad \text{on } \Gamma_{\text{Dir}}, \quad (K\varepsilon(\mathbf{u}) + K_v\varepsilon(\mathbf{u}_t) + \theta\mathbf{1})\mathbf{n} = \mathbf{g} \quad \text{on } \Gamma_{\text{Neu}} \times (0, T),$$

$$(K\varepsilon(\mathbf{u}) + K_v\varepsilon(\mathbf{u}_t) + \theta\mathbf{1})\mathbf{n} + \chi\mathbf{u} + \partial h_{-\infty,0] }(\mathbf{u} \cdot \mathbf{n})\mathbf{n} \ni \mathbf{0} \quad \text{on } \Gamma_{\text{Cont}} \times (0, T),$$

where $-\chi\mathbf{u} - \partial h_{-\infty,0] }(\mathbf{u} \cdot \mathbf{n})\mathbf{n}$ on Γ_{Cont} is the reaction

The PDE system: the evolution of the adhesion

We consider on Γ_{Cont}

$$\chi_t - \Delta \chi + \partial \mathbf{l}_{[0,1]}(\chi) \ni -\lambda'(\chi)(\theta_s - \theta_{\text{eq}}) - \frac{1}{2}|\mathbf{u}|^2 \quad \text{in } \Gamma_{\text{Cont}} \times (0, T)$$

$$\partial_n \chi = 0, \quad \text{on } \partial \Gamma_{\text{Cont}} \times (0, T)$$

- ▶ $\partial \mathbf{l}_{[0,1]}(\chi) \Rightarrow \chi \in [0, 1]$ (physical consistency)

$$\partial \mathbf{l}_{[0,1]}(\chi) = \begin{cases}]-\infty, 0] & \text{if } \chi = 0 \\ 0 & \text{if } 0 < \chi < 1 \\ [0, +\infty[& \text{if } \chi = 1 \end{cases}$$

- ▶ λ (quadratic) function, related to the latent heat
- ▶ θ_s temperature of the glue, θ_{eq} constant
- ▶ $-\frac{1}{2}|\mathbf{u}|^2$ source of damage due to macroscopic movements

The PDE system: the temperature equations

- ▶ The **entropy equation** (rescaled energy balance) for θ in Ω

$$\begin{aligned} \partial_t(\log \theta) - \operatorname{div} \mathbf{u}_t - \Delta \theta &= h \text{ in } \Omega \times (0, T), \\ \partial_n \theta &= \begin{cases} 0 & \text{on } \partial\Omega \setminus \Gamma_{\text{Cont}} \times (0, T) \\ -\chi(\theta|_{\Gamma_{\text{Cont}}} - \theta_s) & \text{on } \Gamma_{\text{Cont}} \times (0, T) \end{cases} \end{aligned}$$

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- ▶ The **entropy equation** for θ_s on Γ_{Cont} is

$$\begin{aligned} \partial_t(\log \theta_s) - \lambda'(\chi)\chi_t - \Delta \theta_s &= \chi(\theta|_{\Gamma_{\text{Cont}}} - \theta_s) \quad \text{in } \Gamma_{\text{Cont}} \times (0, T) \\ \partial_n \theta_s &= 0 \quad \text{on } \partial\Gamma_{\text{Cont}} \times (0, T) \end{aligned}$$

The complete PDE system: difficulties

$$\begin{aligned}
 & -\operatorname{div}(K\varepsilon(\mathbf{u}) + K_v\varepsilon(\mathbf{u}_t) + \theta\mathbf{1}) = \mathbf{f} \quad \text{in } \Omega \times (0, T), \\
 & \mathbf{u} = \mathbf{0} \quad \text{on } \Gamma_{\text{Dir}} \times (0, T), \quad (K\varepsilon(\mathbf{u}) + K_v\varepsilon(\mathbf{u}_t) + \theta\mathbf{1})\mathbf{n} = \mathbf{g} \quad \text{on } \Gamma_{\text{Neu}} \times (0, T), \\
 & (K\varepsilon(\mathbf{u}) + K_v\varepsilon(\mathbf{u}_t) + \theta\mathbf{1})\mathbf{n} + \chi\mathbf{u} + \partial I_{[-\infty, 0]}(\mathbf{u} \cdot \mathbf{n})\mathbf{n} \ni \mathbf{0} \quad \text{on } \Gamma_{\text{Cont}} \times (0, T), \\
 & \chi_t - \Delta\chi + \partial I_{[0, 1]}(\chi) \ni -\lambda'(\chi)(\theta_s - \theta_{eq}) - \frac{1}{2}|\mathbf{u}|^2 \quad \text{in } \Gamma_{\text{Cont}} \times (0, T), \\
 & \partial_n\chi = 0 \quad \text{on } \partial\Gamma_{\text{Cont}} \times (0, T) \\
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 & \partial_n\theta_s = 0 \quad \text{on } \partial\Gamma_{\text{Cont}} \times (0, T), \quad +\text{Cauchy conditions}
 \end{aligned}$$

→ **singular character of the θ, θ_s -equations** (θ -equation is coupled with a **third type boundary condition**)

→ we deduce directly $\theta, \theta_s > 0$, crucial for **thermodynamical consistency!**



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 \end{aligned}$$

→ **(quadratic) coupling** terms on the boundary

→ we need **sufficient regularity** on θ and \mathbf{u} to control their **traces**.

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$$\partial_n\theta_s = 0 \quad \text{on } \partial\Gamma_{\text{Cont}} \times (0, T), \quad +\text{Cauchy conditions}$$

→ **non-smooth (multivalued) constraints** on χ and $\mathbf{u} \cdot \mathbf{n}$

The existence theorem

Theorem. Given initial data

$$\begin{cases} \theta_0 \in L^1(\Omega), \log(\theta_0) \in L^2(\Omega), \theta_{s,0} \in L^1(\Gamma_{\text{Cont}}), \log(\theta_{s,0}) \in L^2(\Gamma_{\text{Cont}}), \\ \mathbf{u}_0 \in H^1(\Omega)^3, \chi_0 \in H^1(\Gamma_{\text{Cont}}) \end{cases}$$

there exist $(\mathbf{u}, \chi, \theta, \theta_s)$ solving the **weak, variational** formulation of the **IBVP**

$$-\operatorname{div}(K\varepsilon(\mathbf{u}) + K_V\varepsilon(\mathbf{u}_t) + \theta\mathbf{1}) = \mathbf{f} \quad \text{in } \Omega \times (0, T),$$

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The existence theorem

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$$\begin{cases} \theta_0 \in L^1(\Omega), \log(\theta_0) \in L^2(\Omega), \theta_{s,0} \in L^1(\Gamma_{\text{Cont}}), \log(\theta_{s,0}) \in L^2(\Gamma_{\text{Cont}}), \\ \mathbf{u}_0 \in H^1(\Omega)^3, \chi_0 \in H^1(\Gamma_{\text{Cont}}) \end{cases}$$

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- we do not approximate $\partial_{l_{[0,1]}}(\chi)$, $\partial_{l_{[-\infty,0]}}(\mathbf{u} \cdot \mathbf{n})$ in the eq.'s for \mathbf{u} and χ

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Uniqueness?

- ▶ **NOT expected** due to the nonlinear structure of the equations, the lack of regularity of θ and the boundary conditions
- ▶ holds for the **approximating problem**

Trajectories on $(0, +\infty)$

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How the trajectories $(\mathbf{u}(t), \chi(t), \theta(t), \theta_s(t))$ behave as $t \rightarrow +\infty$?

- ▶ need **uniform estimates** on the solutions independent of the final time T
- ▶ **further requirement** on the entropy flux through Γ_c

$$\partial_n \theta = -(\chi + c)(\theta|_{\Gamma_c} - \theta_s), \quad c > 0 \text{ on } \Gamma_c$$

\rightsquigarrow residual flux even if $\chi = 0$

(crucial to obtain a L^2 -estimate for $\theta|_{\Gamma_c} - \theta_s$)

Long-time a priori estimates

Due to the **dissipative character of the system**

$$|\theta|_{L^\infty(1,+\infty;H^1(\Omega))} + |\nabla\theta|_{L^2(0,+\infty;L^2(\Omega))} \leq C$$

$$|\theta_t|_{L^2(1,+\infty;L^p(\Omega))} \leq C \quad \text{for } p \leq 12/7$$

$$|\theta_s|_{L^\infty(1,+\infty;H^1(\Gamma_{\text{Cont}}))} + |\nabla\theta_s|_{L^2(0,+\infty;L^2(\Gamma_{\text{Cont}}))} \leq C$$

$$|\partial_t\theta_s|_{L^2(1,+\infty;L^q(\Gamma_{\text{Cont}}))} \leq C, \quad \text{for } q < 2$$

$$|\theta|_{\Gamma_{\text{Cont}}} - \theta_s|_{L^2(0,+\infty;L^2(\Gamma_{\text{Cont}}))} \leq C$$

$$|\chi|_{L^\infty(1,+\infty;H^2(\Gamma_{\text{Cont}}))} + |\chi_t|_{L^2(1,+\infty;H^1(\Gamma_{\text{Cont}}))} \leq C$$

$$|\mathbf{u}|_{L^\infty(0,+\infty;H^1(\Omega)^3)} + |\mathbf{u}_t|_{L^2(0,+\infty;H^1(\Omega)^3)} \leq C$$

$$|\partial_t(\log\theta)|_{L^2(0,+\infty;H^1(\Omega)')} + |\partial_t(\log\theta_s)|_{L^2(0,+\infty;H^1(\Gamma_{\text{Cont}})')} \leq C$$

⇒ the “**energy**” and the “**dissipation**” are **uniformly bounded**

⇒ the solutions trajectories **converge** in a suitable sense to some cluster points as $t \rightarrow \infty$

The ω -limit set

The set of the **possible cluster points** $(\mathbf{u}_\infty, \chi_\infty, \theta_\infty, \theta_{s\infty})$ of the solutions trajectories

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- ▶ thermomechanical equilibrium (**no dissipation**) in the limit $t \rightarrow \infty$.